

A Facial Recognition System in MATLAB Using Convolutional Neural Networks

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Abstract: Facial expression recognition systems have attracted a whole lot of research interest inside the discipline of artificial intelligence. Many established facial expression reputation (FER) structures follow standard devices gaining knowledge of to extract photograph features, and those strategies generalize poorly to formerly unseen statistics. This mission builds upon the latest research to categorize pictures of human faces into discrete emotions categorizing the usage of Convolutional Neural Networks (CNN). In this way of facial recognition, a Convolutional Neural networks (CNN) based face popularity approach is executed. This GoogleNet based CNN consists of convolution layers, Rectified-Linear Unit (Re-Lu) layers, pooling layers and fully-connected layers. SGDA is useful for teaching the function classifier & extractor that could derive the feature capabilities and section those routinely. The over-fitting problem is resolved by using the Dropout method. Caffe, which is used for aspect derivation, is used throughout the practicing and the experimenting process.

Keywords: CNN, GoogleNet, SGDA.

1. Introduction

A surface appearance is the seen appearance of the used state, intellectual usage, purpose, character, and psychiatry of someone and plays an effective role in comparative studies.

Human feature reactions can be effortlessly categorized into 7 simple feelings: glad, unhappy, amazement, terror, rage, abhorrence, and impartial. Input facial feelings are conveyed via the beginning of specific units of facial muscle tissue. They could be understated, but complex, signals in an expression often comprise a plentiful quantity of records about our condition of thoughts.

Automated recognition of facial reactions could be a critical element of normal human-system boundaries. It could additionally be utilized in interactive technology and in hospitalizing exercise. It is studied for a long amount of time and acquired advancement in later years.

Although a whole lot of development has been made, identifying facial reactions with excessive perfection still is very tough because of the difficulty and kind of reactions.

On a daily routine, people normally identify reactions by function capabilities, exhibited as part of a facial reaction. As an example, joy is unarguably related to a grin or angling of the lips. Similarly, different reactions are categorized by means of different angling regular to a specific reaction. A study about the automatic identification of facial reactions tells about the issues around the illustration and classification of stationary or active features of these angles that are used to pigment faces.

In machine training and learning, a Convolutional Neural Community (CNN, or ConvNet) is a kind of man-made neural community that employs feed forward mechanisms, wherein the link sample among its neurons is encouraged with the aid of the visual features present in animal's organization. Separate cortical neurons easily respond to stimuli in a limited place of space referred to as the receptive discipline. The receptive fields of various neurons in part overlay such that they piece the field of vision. The reply of a character neuron to stimuli inside its

receptive subject can come close mathematically through a convolution process. CNNs have been encouraged by way of organic procedures and are versions of multi-layer perceptron

intended to use low quantities of pre-processing. They have extensive usages in photo and video popularity and natural language processing.

The convolutional neural community is likewise indifferent to shift and they are also called Area Invariant Synthetic Neural Community (SIANN), that is known primarily because of its common weights construction and change invariance traits. GoogleNet is one of the convolutional neural networks that helped improve the sphere of Deep getting to know. It is far from a 22-layer deep CNN community that may be a version of the inception network, a Deep CNN advanced by using researchers from Google. The GoogleNet architecture solved most of the problems that massive networks confronted, mainly via the Inception module's utilization. The inception module is a neural community structure that leverages feature detection at distinct scales thru convolutions with distinctive filters and decreases the computational cost of training an in-depth community via dimensional discount.

2. Review of Literature

Multiple research papers include Image-Based Facial Recognition using CNN on Matlab. One of the methods [A] uses a network that has convolution layers, pooling layers, fullyconnected layers, and one Softmax regression layer. Also, SGDA is employed to teach the characteristic classifier & the function extractor, where the facial properties are extracted

and classified routinely. For the duration of the schooling and

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checking out process, the Caffe is implemented. The coaching and the validation accuracies are found out to be 71% and 75% on an average of 10 different training sessions of GoogleNet.

In the research paper [B], the face recognition system has its basis on the Principal Component analysis and the feed-forward neural community. The ordinary face recognition systems had been advanced earlier but didn't work enough on make-up, so it is developed with a device inclusive of phrases which might be the Principal Component Analysis segment, and the phase that classifies neural networks into different segments. The Principal Component Analysis segment is implemented to measure the function projection vector of a given face that is then used for aspect identification with the aid of the feedforward neural community. The proposed PCA and neural community-based totally identity machine affords development on the identification charges, while compared with a classifier that segments a face based totally on the PCA and Euclidean Distance, all the databases will be created with some of the faces with distinct makeups.

In the research paper [C], PCA Algorithm has been used for saving databases of images like varied reactions of faces and identification of facial aspects for further protection. A system

that recognises faces generally has various modules, mostly four, as face sectioning, regularising, aspect derivation, and matching. A slumbering period in unmanned face recognition on a low dimensional face representation was inherited using the Principal Component Analysis (PCA). More extraordinary feats in facial recognition includes the Fischer face method which applies Linear Discriminant Analysis. It also explains that the Linear Discriminant Analysis method is used after a Principal Component Analysis so that the accuracy is increased.

In the research paper [D], the results of the said Convolutional Neural Network (CNN) with multiple popular picture identification methods such as PCA, Local Binary Patterns

Histograms (LBPH), and K–Nearest Neighbour (KNN) is tested. All the tests were implemented on the ORL database and the results were examined. The result showed that the Local Binary Patterns Histograms provided superior results to both the Principal Component Analysis and K-Nearest Neighbour. For CNN it is observed that the best identification accuracy is 98.3 %. The said method based on Convolutional Neural Network outdoes the other well recognised methods.

3. Methodology and Implementation

The facial expression recognition system is implemented using a convolutional neural network.

This project uses the GoogleNet CNN architecture. GoogleNet, a convolutional neural network consisting of 22 layers that is a variant of Inception Network, a deep convolutional neural network developed by Google researchers.

A. Transfer Learning

Designing a brand-new network, developing the architectures with excessive accuracy, specification of the beginning heaviness of the underlying nodes effectively is a time-eating and time-consuming procedure. When we employ transferrable learning techniques, we will have a pre-defined and evolved network equipped to study new capabilities to execute new responsibilities. In this way, transfer learning facilitates getting the desired things done by using neural network with less effort. We can easily implement face detection and classification using CNN with comparatively less effort by changing the already existing GoogleNet. The practiced image category networks are nicely-educated and might section pics into different high accuracy classes. But, the difficulty of a network which is already trained is that it can classify features that is educated to categorize. Think that the GoogleNet is skilled to categorize one thousand one-of-a-kind objects. If there's an object apart from those one thousand objects, then the classification will be failed. But there might be ways to use the present network to coach it for classifying the dataset. This is transfer learning. Deep learning method is, where an already existing network is made use of a starting node to learn a new task. This concept is applied here to train the GoogleNet for facial recognition.

B. Overview of the Process

CNN has multiple layers. We can separate those layers into the layers that learn features and layers that are specific to doing tasks. Aspects such as colors, corners, and bubbles which are

on low levels are learnt by the feature learning layers whereas the features which are task specific are learnt by the task specific layers. For an instance, if the network's task is to differentiate vehicle and non-vehicle images, then the vehicles' features are learnt by the task specific layers.

In the approach of transfer learning, the layers that are specific to tasks are excluded from the existing layers of the network and user-defined layers are included to train the system for further desired tasks. The training is done with new dataset and then validation and testing are done. If the training is done in the right way with a dataset that is effective, then the network

can easily differentiate the newly learned objects.

The entire transfer mastering technique is split into 6 steps. These steps are:

- 1. Preparation of the dataset.
- 2. Loading the dataset.
- 3. Loading the already existing network.
- 4. Replacement of the task specific layers.
- 5. Augmentation of pictures for Over-fitting prevention.
- 6. Network training.
- 7. Testing.
- C. Working of CNN

There are four layered principles to apprehend in CNN:

- 1. Convolution.
- 2. Rectified Linear Unit (Re-Lu).
- 3. Pooling.
- 4. Fully Connected Layer.

In order for the computer to identify the pixels, white pixels are assumed to be -1 whereas the black pixels are assumed to be 1. This is implemented to differentiate pixels in a basic binary classification. If the values between a normal 'X' image and another different rendition of 'X' are normally searched and

compared, a lot of missing pixels will be obtained. In order to fix this, small pixel patches (filters) are taken and matched in the corresponding locations nearby to check whether a match is obtained. By implementing this, CNN becomes better at finding similarities than entirely attempting to match the full input image.

1) Convolution Layer

- There are 4 steps involved in convolution:
 - 1. Lining up the function as well as the photograph.
 - 2. Multiplying each and every pixel of the image by analogous feature pixel.
 - 3. Adding the values and arriving at the total sum.
 - 4. Dividing the sum by the total quantity of pixels inside the feature.

A filter image is considered and a pixel taken from it is multiplied with the per-existing image and another buffer feature image gets to store the product. The values are added which leads to the total sum. Then, it is divided by the total quantity of the pixels in the feature image. The resultant value is placed at the center of the filtered image. Now, this filter is moved around and the same operation is carried out at any other pixel in the same image. In the same manner, the feature is moved to each and every other image position and observes the matching of the feature with that area.

Similarly, the same convolution is performed with each and every filter to obtain those filters' convolution. The resulting strength of the signal does not depend upon the locations of the

features, but just checks the presence of the features. So, a symbol could be present in various places and the CNN algorithm would still be capable of finding it.

2) Re-LU Layer

Rectified Linear Unit (Re-LU) layer, an activation function, only turns on a node if the entry rises more than a particular quantity, while the entry is beneath zero, the output is zero.

However, when the center rises above a particular threshold, there will be a linear relationship between the independent and the dependent variable. The purpose is removing all the negative values after the convolution. All the negative values

become zero whereas the positive values are left untouched. The convolution layer inputs are "smoothened" and the noise and variation sensitivity of the filters are reduced. This particular process is known as sub-sampling and may be accomplished with the aid of taking averages or taking the maximum over a signal sample.

3) Pooling Layer

The stack of the image is reduced to a smaller size (shrunk) in the layer of pooling. Pooling is

executed after going through the Re-Lu layer. The following steps are involved:

- Picking up a window size of dimension 2*2 (usual).
- Picking up a stride.
- Walking the window matrix across the images (filtered).
- Taking the maximum value from each window.

The window size is selected to be 2 and a desired value is chosen from the available 4. The maximum value available among the 4 values is 1 and it is picked. The initial 7×7 matrix came down to 4×4 after pooling. Then the window is moved

across the entire image.

The same operation is repeated for all the chosen filters. After the 1st pass, these three operations are performed in a loop.

The fully connected layers are last layers in the network, which means in subsequent layers, the preceding layers neuron are connected with each and every neuron.

The classification actually happens in the fully connected layer. Then a single list is made of the filtered and shrunk images.

When the values of the elements (1,4,5,10 and 11) are high, then it can be classified that the image is 'X'. The method is the same for any other alphabets. When particular values are rearranged, they could also be mapped to a number or a letter that we need.

4) Image Prediction Using CNN

The system training is completed and testing can be carried out after this. A 12-element vector, using a random letter as the input via all the network layers is obtained. By comparing a list of values of 'X' and 'O' with the obtained values after the output, the predictions are made. The values of the elements which are high (1, 4,5,10 and 11) are added from the 'X' table and the sum is five. A similar process is done with the image of the input. Upon division of both the values, a probability match of 0.91 is obtained.



Fig .1. Comparison with O

For comparison with vector 'O', the probability is 51 percent. It can be concluded that the image that is fed as an input is 'X'. So, this is how CNN works.

Table 1		
Training and validation accuracy		
Training Session	Training	Validation
Index	Accuracy (%)	Accuracy (%)
1	100.00	100.00
2	70.00	65.56
3	20.00	33.33
4	98.89	98.89
5	70.00	66.67
6	40.00	66.67
7	100.00	92.22
8	90.00	100.00
9	100.00	100.00
10	30.00	33.33
Average	71.89	75.67

Table 1 Training and validation accuracy



Fig. 2. Matching of filters



Fig. 3. Output of the facial recognition system

4. Conclusion

In this project, a GoogleNet architecture-based convolution neural network is implemented for recognizing and classifying human faces. The training and the validation accuracies are found out to be 71% and 75% on an average for 10 different training sessions of GoogleNet. After the course, more sophisticated proposal region generation methods can be explored and implemented to further increase the detection speed. By combining the good aspects of GoogleNet and other convolutional neural network architectures it is possible to increase the detection and classification accuracies.

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